I4U Submission for the 2010 NIST Speaker Recognition Evaluation Submission

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1. INTRODUCTION

The *I4U* team is a consortium of *one* institute and *four* universities comprising of Institute for Infocomm Research (IIR), University of Science and Technology of China (USTC), University of New South Wales (UNSW), Nanyang Technological University (NTU), and University of Eastern Finland (UEF). The *I4U* team submitted two systems for the 2010 NIST Speaker Recognition Evaluation (SRE), namely the *I4U-Primary* and *I4U-Alternate*, as described in this file I4U_SystemDescription.pdf. The *primary* and *alternate* systems are based on the combination of multiple classifiers and acoustic features. Both submissions include the results for five training-test conditions as indicated in Table I. In particular, included in this submission (I4U.zip) are:

1. I4U_1_10sec_10sec_primary_llr.txt
2. I4U_1_core_10sec_primary_llr.txt
3. I4U_1_8conv_10sec_primary_llr.txt
4. I4U_1_core_ core_primary_llr.txt
5. I4U_1_8conv_core_primary_llr.txt
6. I4U_2_10sec_10sec_alternate_llr.txt
7. I4U_2_core_10sec_ alternate_llr.txt
8. I4U_2_8conv_10sec_ alternate_llr.txt
9 I4U_2_core_ core_ alternate_llr.txt
10 I4U_2_8conv_core_ alternate_llr.txt
11 I4U_SystemDescription.pdf

The confidence scores of our submission can be interpreted as log-likelihood scores.

Table I *I4U* submission (both primary and alternate) includes five training-test conditions.

		Test segment condition		
		10sec	core	summed
Training condition	10sec	✓		
	core	✓	✓	
	8conv	✓	✓	
	8summed			

Table II Classifiers (both generative[+] and discriminative[*]) and acoustic features used for the *I4U* speaker recognition system.

Classifier	Features
GMM-UBM-JFA[+]	LPCC
GMM-SVM-KL[*]	PLP
GMM-SVM-BHATT[*]	MFCC
GMM-SVM-FT[*]	SCM-SCF
	SWLP

2. SYSTEM DESCRIPTION

The *I4U* system employs four classification techniques used in combination with five different cepstral features. The first classifier is based on the generative GMM-UBM [1] approach, while the remaining three classifiers are based on discriminative SVM techniques, as listed in Table II. Various, but not all, combinations of feature types and classifiers were used. In the following, we first present the

feature extraction process. Then we briefly introduce the four classifiers. Finally, we report the fusion technique.

2.1 Feature Extraction

2.1.1 PLP

The HTK toolkit is used to extract the PLP features. Speech samples were segmented into frames with a 20ms Hamming window progressing at a 10ms frame rate. Each speech frame was parameterized with 13 PLP coefficients and their first and second derivatives (i.e., a 39-dimensional feature vector). Further processing includes RASTA filtering, VAD detection [2], CMS and Gaussianization were applied.

2.1.2 LPCC

The SPTK toolkit was used to extract the LPCC features. Speech samples were segmented into frames with a 30ms Hamming window progressing at a 10ms frame rate. Each speech frame was parameterized with 18 order LPCC coefficients. Using on the first derivative, a 36-dimensional feature vector was obtained. Further processing includes RASTA filtering, VAD detection [2], CMS and Gaussianization were applied.

2.1.3 MFCC

The Abacus toolkit was used to extract the MFCC features. 16 order MFCC was generated with a 30ms window at a 12.5ms frame rate. The 16-order MFCC, 16-order first and 14-order second derivatives were appended to form the final 46-dimensional feature vector. Spectral subtraction based noise reduction method [3] was used to assist the energy-based VAD to remove silence frames and to retain only the high quality speech frames for all the telephone and telephone-microphone data. For the interview-microphone style channel data, the frame selection is based on the logical AND between the energy based VAD and ASR transcripts provided by NIST. Finally, the selected feature vectors were processed by RASTA filtering and mean-variance-normalization (MVN).

2.1.4 SCM-SCF

An energy-based speech detector which was applied to discard silence and noise frames. Features were extracted from 20ms frames, overlapped by 10ms. According to the algorithm described in [4], 14 Mel-spaced Gabor filters were used to decompose the speech signal into 14 sub-band signals, resulting in 28 dimensions of SCF-SCM feature vector. Spectral centroid frequency (SCF) is the weighted average frequency for a given subband. Since this measure captures the center of gravity of each subband, it can detect the approximate location of formants, which are manifested as peaks in neighbouring subband. On the other hand, spectral centroid magnitude (SCM) is the weighted average magnitude for a given subband. As the spectral centroid magnitude is the magnitude at the position of the spectral centroid frequency, it will carry formant related information which is useful for speaker recognition.

2.1.5 SWLP

The SWLP feature extraction was based on the recent work [5]. The method gives an alternative way to compute the MFCC features, where the FFT spectrum is replaced by an all-pole spectrum obtained through a stabilized weighted linear prediction analysis [6]. All the other steps are kept untouched. The idea in the SWLP analysis is to use a short-term energy based weighting function to weight the prediction residual (error signal) so that the all-pole modeling will be focused on locally high-energy portions of the given speech frame. The high-energy portions are assumed to be less corrupted by additive background noise and, from a phonetic viewpoint, they correspond to the glottal closed phase [6] which should give as a more reliable vocal tract model.

2.2 Classifiers

2.2.1 GMM-UBM-JFA

Joint factor analysis (JFA) [8, 9] is a modeling technique used to treat the problem of speaker and channel variability, built on top of the classical GMM-UBM approach [1]. NIST SRE04 1side training data was used to generate a gender-dependent UBM model with 1024 Gaussian mixtures. Switchboard II data, SwitchBoard Cellular and SRE04 corpus were used to train a speaker space with 300 speaker factors. The diagonal matrix was trained using SRE04 1side train and test data. For channel space training, a telephone channel space with 100 channel factors was trained based on the telephone data from SRE04, SRE05, SRE06 and SRE08 data. Microphone channel space (50 channel factors) was trained based on the microphone data from SRE05, SRE06 and SRE08. Finally, interview data from the MIXER5, SRE08 and SRE08-followup were used to train an interview channel space with 100 channel factors. The full channel space (250 channel factors in total) was formed by appending the above three sub-spaces.

TZNORM was applied based on the train (TNORM) and test (ZNORM) conditions to different systems [10]. For ZNORM, we use SRE05 1side training utterances for telephone data and SRE05 microphone utterances for microphone and interview data. For TNORM, we use SRE06 1side training models for telephone data and SRE06 microphone models for interview data.

2.2.2 GMM-SVM-KL

The GMM-SVM system was designed based on the work reported in [11, 12]. Given an utterance for GMM adaptation, only mean vectors are adapted via MAP, while its weights and covariance matrices are kept unchanged. The mean vectors of mixture components in the GMM are then concatenated to form a supervector, which is used as

input to SVM. The mean vectors are normalized by its standard deviation and weighted by the squared root of the weights of the Gaussian mixtures. This normalization step was motivated from the Kullback-Liebler (KL) divergence perspective, and the resulting kernel was referred to as the KL kernel. LibSVM [13] was used to train the SVM models and the NAP [11] with a corank of 60 was used for channel compensation in the supervector space.

The system was designed to be gender-dependent. The UBMs, with a model size of 1024, were trained using SRE04 data. The NAP loading matrix was trained using SRE04 telephone, SRE05 microphone, SRE06 microphone, MIXER5 and SRE08-followup data. SRE04 and MIXER 5 data were used to form the SVM background.

2.2.2 GMM-SVM-BHATT

This subsystem follows the conventional GMM-SVM architecture, as mentioned above, except that a different kernel metric was used, which we refer to as the Bhattacharyya kernel [14]. Different also from the KL kernel, the Bhattacharyya kernel allows the adaptation of both mean vectors and covariance matrices. Compared to the KL kernel, the Bhattacharyya kernel can better reflects the salient characteristics of the speaker GMM, where the supervector represents the relative distance to the UBM instead of an absolute point in the vector space. Similar training and development data as mentioned in Section 2.2.2 were used.

2.2.4 GMM-SVM-FT

The FT-SVM method characterizes a speaker by the difference between the speaker and a cohort of background speakers in the form of feature transform (FT) [15]. The FT is a linear regression function that projects speaker dependent features to speaker independent ones, also known as an affine transform. It consists of two sets of parameters, bias vectors and transform matrices. The former, representing the first order information, is more robust than the latter, the second order information. We propose a flexible tying scheme that allows the bias vectors and the matrices to be associated with different regression classes, such that both parameters are given sufficient statistics in a speaker verification task. We formulate a maximum a posteriori (MAP) algorithm for the estimation of feature transform parameters, that further alleviates the possible numerical problem. The FT parameters are then vectorized and compared via a support vector machine (SVM). Similar training and development data as mentioned in Section 2.2.2 were used.

2.3 Fusion

Our primary and alternate systems adopted the following linear fusion model:

$$\hat{s} = w_0 + \sum_{i=1}^{N} w_i s_i \quad (1)$$

where s_i is the score from the ith subsystems and N is the total number of subsystems. We optimize the weights based on the minimum DCF criterion. The weights are tuned on development set designed based on the NIST SRE08 and SRE08 follow-up data. The optimum weights were found via brute-force search.

3. TRAINING DATA

The training data were drawn primarily from NIST SRE 2004, SRE 2005, and SRE 2006, Mixer 5 interview data, SRE 2008, Follow-up data for SRE2008, and Switchboard. Only English samples were used. We designed a development set to match the condition anticipated for SRE10. In particular, the probability of target was set to 0.01 for the development data drawn from the SRE08 and follow-up data. The other datasets were used for UBM training, channel compensation, and score normalization.

4. PROCESSING SPEED

The processing speed of the system is measured based on the Xeon 2.13 GHz processor with 1 Gb RAM. The breakdown of the runtime factor is summarized in Table III for each of the classifiers.

Table III The runtime factors comparison of classifiers used in the system.

Classifier	Runtime Factor (×RT)
GMM-UBM-JFA	0.50
GMM-SVM-KL	0.08
GMM-SVM-BHATT	0.10
GMM-SVM-FT	0.28

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