



The CRIM System for the NIST 2005 SRE

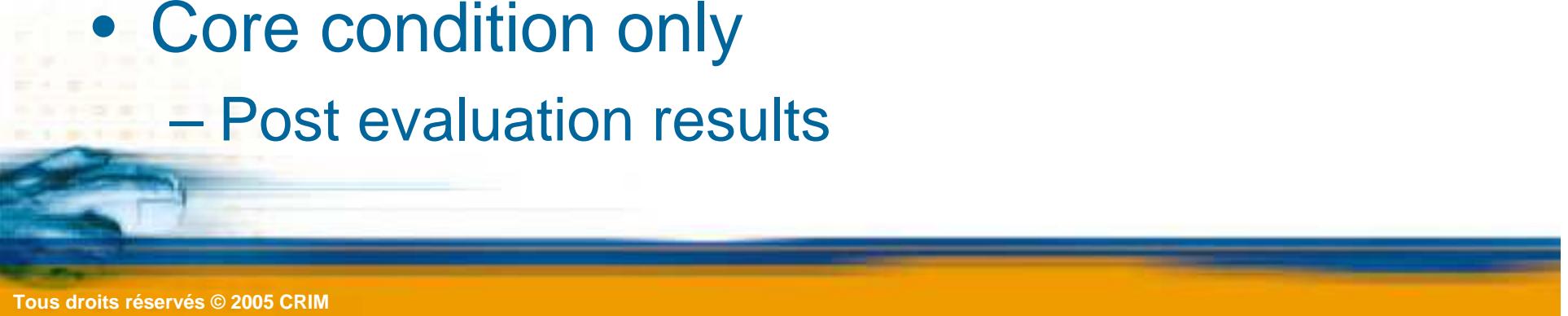
Corpus-Based Models of Speaker and Channel Variability

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Objectives

- Explore new ways of modeling utterance and session variability with large corpora
- Lots of data available but almost all speakers are either landline or cellular
- See if factor analysis can be simplified
 - Eigenchannel modeling
- Core condition only
 - Post evaluation results



Utterance Variability I: Classical MAP



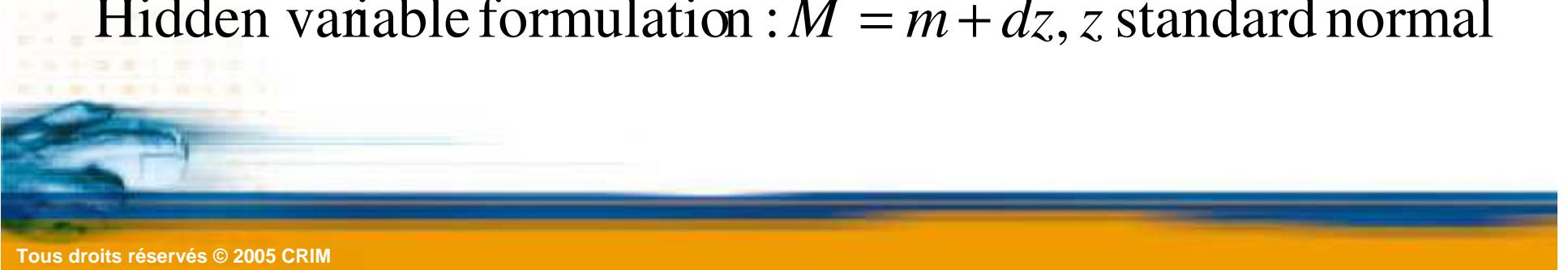
M = supervector for an utterance (conversation side)

m = speaker-independent supervector

d^2 a diagonal covariance matrix

Assumption: M normal with mean m , covariance d^2

Hidden variable formulation : $M = m + dz$, z standard normal



Utterance Variability II: Eigenvoice MAP



Assumption: M normal with mean m , covariance vv^*
 v is a rectangular matrix of low rank

Equivalently: $M = m + vy$, y standard normal

M is a linear combination of m and the columns of v
(speaker space)



Utterance Variability III: Factor Analysis MAP



Assumption : $M = m + vy + dz$, y and z standard normal

M normal with mean m , covariance $d^2 + vv^*$

(i.e. a factor analysis in the sense of Rubin & Thayer)

Components of y are *speaker factors*

dz is a residual which compensates for the fact

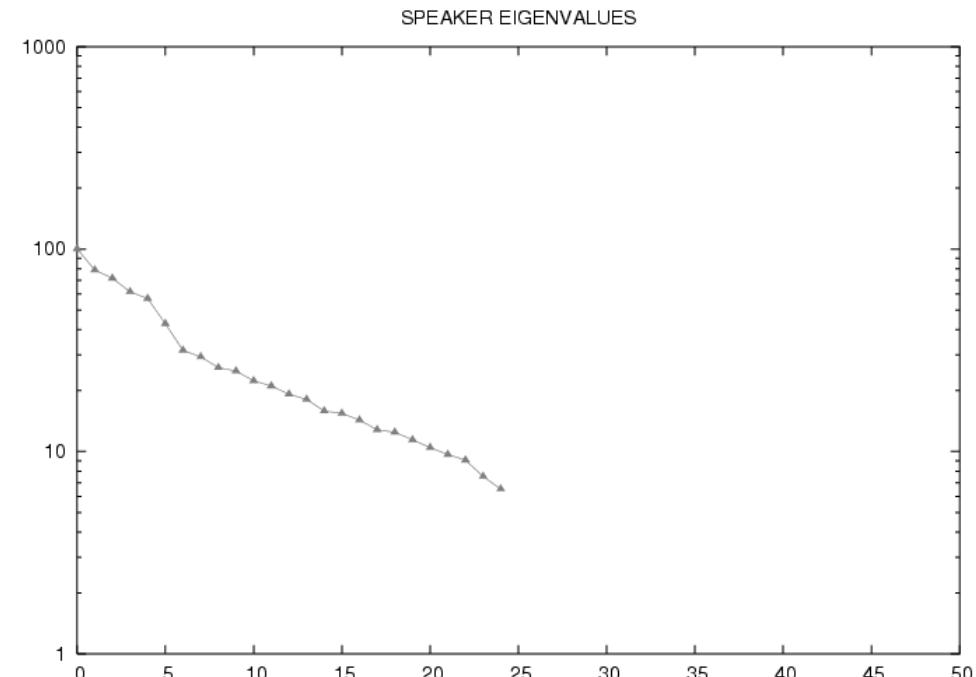
that the speaker space constraint may be too stringent

Utterance Variability (25 eigenvoices, female data)



$$\text{tr}(d^2) = 77$$

$$\text{tr}(vv^*) = 730$$



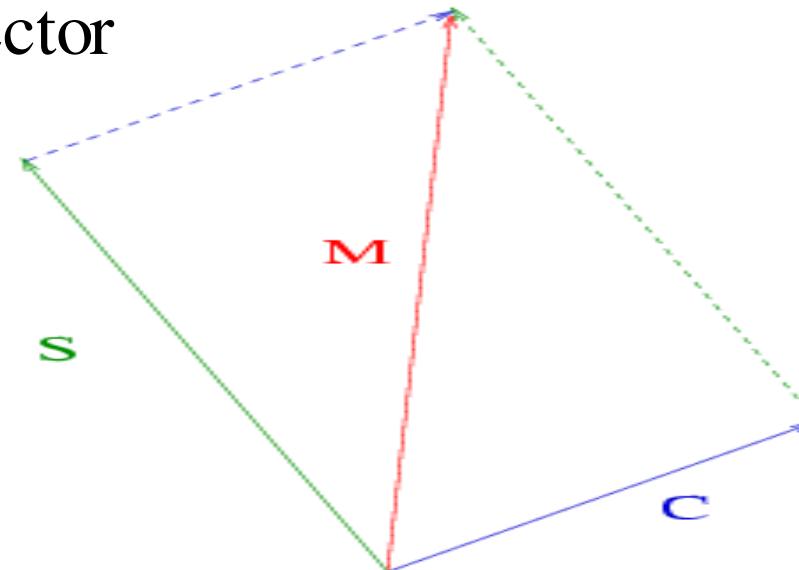
Channel Variability I: Joint Factor Analysis and Feature Mapping

S = speaker supervector

C = channel supervector

M = speaker + channel supervector

$$M = S + C$$

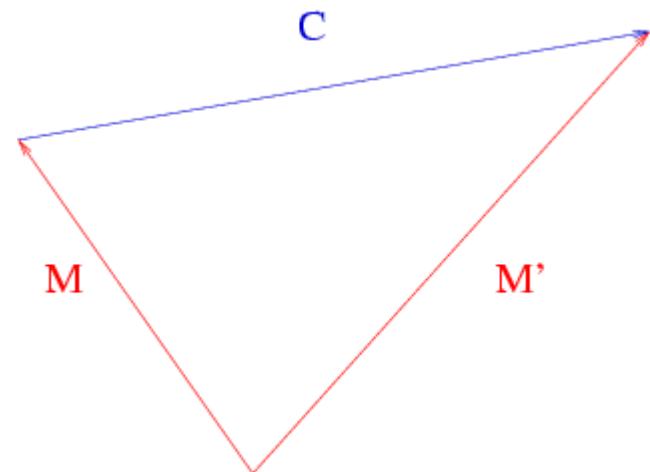


Channel Variability II: Eigenchannel Modeling and Speaker Model Synthesis

M, M' = speaker + channel supervectors

C = channel supervector

$$M' = M + C$$



Channel Variability III: Eigenchannel MAP



M and M' = supervectors for 2 utterances by the same speaker

Assumption: $M' = M + ux$, x standard normal

u rectangular, low rank

Components of x are *channel factors*

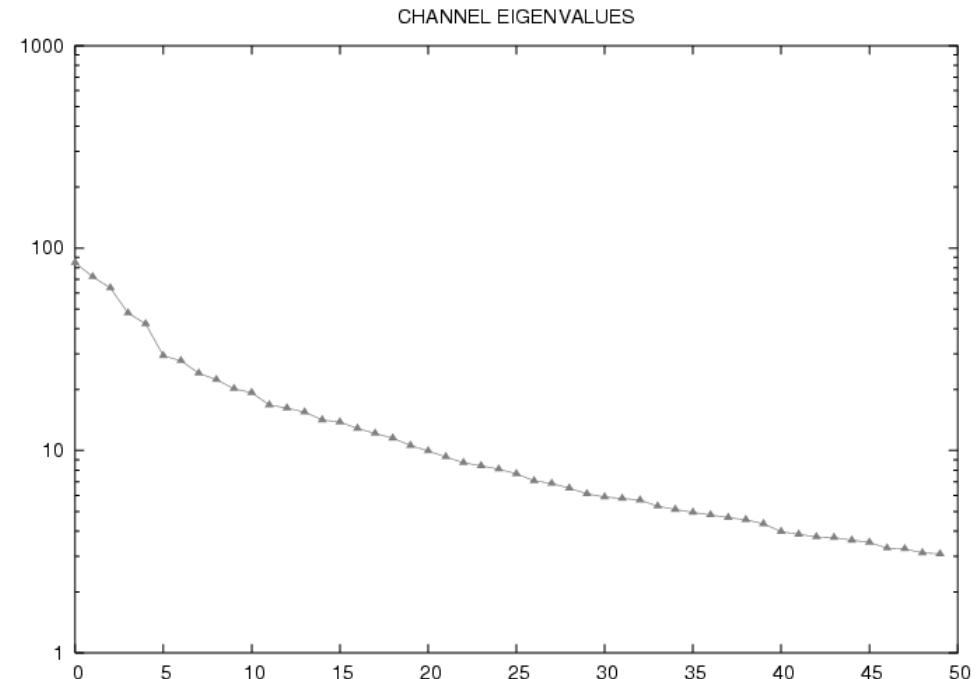
channel space = range (uu^*)

eigenchannels = eigenvectors of uu^*



Channel Variability (50 eigenchannels)

$$\text{tr}(uu^*) = 742$$



Likelihood Function for Speaker Recognition



Use the enrollment data to estimate supervector M for hypothesized speaker s (factor analysis MAP)

M' = supervector for test recording

$$M' = M + ux$$

$$P(\text{test data} | s) = \int P(\text{test data} | M' = M + ux) N(x | 0, I) dx$$



Model Configuration (official submission)

- Gender-dependent
- 2,048 Gaussians per GMM
- 25 speaker factors, 50 channel factors
- 12 cepstral coefficients + log energy
- Feature warping
- Silence detection with .ctm files
- Only attempted core condition
- T-norm



Various Model Configurations (2048 Gaussians, T-Norm)



Eigen Voices	Eigen Channels	EER	DCF
25	50	11.7%	0.042
5	50	11.7%	0.036
5	25	10.2%	0.036
0	25	11.7%	0.038

T-Norm, Z-Norm and ZT-norm

5 eigenvoices, 25 eigenchannels

	EER	DCF
T- NORM	10.2%	0.036
Z-NORM	13.8%	0.047
ZT-NORM	9.5%	0.034

T-Norm, Z-Norm and ZT-norm

0 eigenvoices, 25 eigenchannels

	EER	DCF
T- NORM	11.7%	0.038
Z-NORM	9.9%	0.034
ZT-NORM	8.7%	0.029

Factor analysis beats eigenchannels (zt norm)

	EER	DCF
Forward	6.9%	0.022
Reverse	6.4%	0.023
Combined	6.6%	0.021

Conclusions

- It seems to have been a mistake to use eigenchannel modeling
 - Factor analysis harder but more powerful
- Could we please have some more data?
 - Eg. Impossible to use these methods on auxiliary microphone data
 - How about a **training set** as well as development and test sets?

