

# PERFORMANCE ANALYSIS FOR A CLASS OF AMPLITUDE MODULATED POLYNOMIAL PHASE SIGNALS

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## ABSTRACT

We consider the parameter estimation problem for a class of amplitude modulated polynomial phase signals (PPS), observed in noise. The main contributions of this paper are: (1) We prove that the High-order Ambiguity Function (HAF) is invariant to certain types of amplitude modulation; thus, phase parameter estimation proceeds as in the constant amplitude case. (2) We derive the Cramér-Rao bounds for both the amplitude and phase parameters, when the additive noise is white Gaussian. (3) We show that the HAF is almost additive for multi-component PPS. (4) We establish the covariance bounds for the nonlinear least squares estimator when the additive noise is (non)Gaussian, and satisfies some weak mixing conditions.

## 1. INTRODUCTION

Many real life signals are nonstationary, and some of them can be modeled as amplitude modulated (AM) and/or frequency modulated (FM) signals. Friedlander and Francos [2] considered the case where both the amplitude and phase are linear combinations of known basis functions; they presented the maximum likelihood (ML) estimator, and derived the corresponding Cramér-Rao bounds (CRB) for the additive white Gaussian noise case.

Polynomial phase signals (PPS) are obtained when the basis functions for the phase are  $\{t^m\}_{m=0}^M$ . Constant amplitude chirp signals ( $M = 2$ ) are studied in [4] and [1], and constant amplitude PPS of general order  $M$  are investigated systematically by Peleg, Porat, and Friedlander (see e.g., [6, Ch. 12], and references therein). Results for (stationary) random amplitude PPS are reported in [7], [8].

In this paper, we consider multi-component PPS with deterministic but time-varying (TV) amplitudes,

$$s(t) = \sum_{l=1}^L \rho_l(t/T; \underline{\theta}_{\rho_l}) e^{j \sum_{m=1}^{M_l} a_{lm_l} t^{m_l}} \quad (1)$$

$t = 0, 1, \dots, T-1$ . The amplitude function  $\rho_l(t/T; \underline{\theta}_{\rho_l})$  is parameterized by  $\underline{\theta}_{\rho_l}$  and satisfies the following assumptions [3]: (a1)  $\rho_l(u; \underline{\theta}_{\rho_l})$  is a real and continuous function of bounded variation for  $u \in [0, 1]$ , and vanishes for  $u \notin [0, 1]$ ; (a2)  $\rho_l(u; \underline{\theta}_{\rho_l})$  is differentiable in  $\underline{\theta}_{\rho_l}$  and the derivative is of bounded variation in  $u$ . The class of functions satisfying (a1) and (a2) includes the constant amplitude model, the transient model, the linear decay model, the polynomial model and so on [3], [10], [11]. Applications of the deterministic AM PPS model include: seismic signal processing (damped multi-component chirps), processing of Doppler radar signals in a fading environment, and modeling of speech signals, to name only a few. Simulation results and details of proofs will be given in [9] and [12].

## 2. AMPLITUDE MODULATION AND HAF

Let us first consider the single component version of (1),

$$s(t) = \rho(t/T; \underline{\theta}_{\rho}) e^{j \sum_{m=0}^M a_m t^m} = \rho(t/T; \underline{\theta}_{\rho}) e^{j \phi(t; \underline{\theta}_{\phi})}, \quad (2)$$

where  $\underline{\theta}_{\phi} := [a_0 \ a_1 \ \dots \ a_M]'$  is the phase parameter vector, and  $\phi(t; \underline{\theta}_{\phi}) := \sum_{m=0}^M a_m t^m$ . The high-order instantaneous moment (HIM) (see e.g., [6, Sec. 12.6]) is defined as

$$\mathcal{P}_M[s(t); \tau] := \prod_{q=0}^{M-1} [s^{(*q)}(t - q\tau)]^{\binom{M-1}{q}}, \quad (3)$$

where  $s^{(*q)}(t) := s(t)$  for  $q$  even, and  $s^{(*q)}(t) := s^*(t)$  for  $q$  odd. The high-order ambiguity function (HAF), is defined as the Fourier Series (FS) of the HIM,

$$P_M[s; \alpha, \tau] := \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} \mathcal{P}_M[s(t); \tau] e^{-j\alpha t}. \quad (4)$$

It can be shown [10, 11] that substitution of (2) and (3) into (4) yields, under (a1)-(a2), for finite  $\tau$ ,

$$P_M[s; \alpha, \tau] = \left[ \int_0^1 [\rho(u)]^{2^{M-1}} du \right] e^{j\tilde{\phi}} \delta(\alpha - \tilde{\omega}) \quad (5)$$

$$\tilde{\omega} := M! \tau^{M-1} a_M, \quad (6)$$

where  $\tilde{\phi}$  is a function of  $M$ ,  $\tau$ ,  $a_{M-1}$ , and  $a_M$  [6, p. 395], and  $\delta(\cdot)$  is the Kronecker delta function.

From (6), we conclude that: *Polynomial phase signals with time-varying amplitudes satisfying (a1) and (a2), have the same HAF, to within a constant scale factor, as the corresponding constant amplitude PPS.*

In practice, we observe a noisy version of (1),

$$x(t) = s(t) + g(t) = \rho(t/T; \underline{\theta}_{\rho}) e^{j \sum_{m=0}^M a_m t^m} + g(t), \quad (7)$$

where it is assumed that: (a3)  $g(t)$  is zero-mean, white circular complex Gaussian with finite variance  $\sigma_g^2$ .

A natural estimate of (3) is  $\hat{\mathcal{P}}_M[s(t); \tau] := \mathcal{P}_M[x(t); \tau]$ , where the latter is defined similar to (3). The HAF estimator is given by

$$\hat{P}_M[s; \alpha, \tau] := \frac{1}{T} \sum_{t=0}^{T-1} \hat{\mathcal{P}}_M[s(t); \tau] e^{-j\alpha t}, \quad (8)$$

and can be efficiently computed via the FFT. It is proved in [10, 11] that  $\hat{P}_M[s; \alpha, \tau]$  is an asymptotically unbiased and mean square sense consistent estimator of  $P_M[s; \alpha, \tau]$ .

Based on (6), one can estimate  $a_M$  from the peak location of  $|\hat{P}_M[s; \alpha, \tau]|$ , multiply  $x(t)$  by  $\exp(-j\hat{a}_M t^M)$ , and

repeat the procedure to obtain  $a_{M-1}$ , and so on. Instead of computing the FT of the HIM estimate, we can also apply high resolution algorithms - such as the Kumaresan-Tufts, matrix pencil, and MUSIC algorithms - to the HIM estimate. Their performance and relative merits are discussed in [10],[11], where special cases of  $\rho(t; \cdot)$  are also considered.

### 3. CRAMÉR-RAO BOUNDS

The log-likelihood function for  $x(t)$  in (7) is given by

$$\Lambda = -\frac{1}{\sigma_g^2} \sum_{t=0}^{T-1} \left| x(t) - \rho(t/T; \underline{\theta}_\rho) e^{j\phi(t; \underline{\theta}_\phi)} \right|^2 \quad (9)$$

If we denote the  $k$ th-element of  $\underline{\theta}_\rho$  by  $\theta_{\rho_k}$ , and the  $l$ th-element of  $\underline{\theta}_\phi$  by  $\theta_{\phi_l}$ , then the entry of the Fisher information matrix (FIM) corresponding to parameters  $\theta_{\rho_k}$  and  $\theta_{\phi_l}$  is  $J_{\theta_{\rho_k}, \theta_{\phi_l}} := -E[\partial^2 \Lambda / \partial \theta_{\rho_k} \partial \theta_{\phi_l}]$ . It is not difficult to show that  $J_{\theta_{\rho_k}, \theta_{\phi_l}} = 0$ , and hence the FIM for the amplitude part is decoupled from that for the phase part. The  $(k, l)$  entry of the FIM for  $\underline{\theta}_\rho$  is

$$J_{\rho, kl} = \frac{2}{\sigma_g^2} \sum_{t=0}^{T-1} \frac{\partial \rho(t/T; \underline{\theta}_\rho)}{\partial \theta_{\rho_k}} \frac{\partial \rho(t/T; \underline{\theta}_\rho)}{\partial \theta_{\rho_l}} \quad (10)$$

$$\rightarrow \frac{2T}{\sigma_g^2} \int_0^1 \frac{\partial \rho(u; \underline{\theta}_\rho)}{\partial \theta_{\rho_k}} \frac{\partial \rho(u; \underline{\theta}_\rho)}{\partial \theta_{\rho_l}} du. \quad (11)$$

From (10), we see that  $J_{\rho, kl} = O(T)$ ,  $\forall k, l$ , and hence  $\text{CRB}(\hat{\theta}_{\rho_k}) = O(T^{-1})$ . Moreover,  $J_{\rho, kl}$  does not involve  $\phi(t)$ , and therefore  $\text{CRB}(\hat{\theta}_{\rho_k})$  is not a function of  $\underline{\theta}_\phi$ .

For the exponentially damped harmonic,  $\rho(t/T) = \rho_o \exp(-bt/T)$ ,  $\underline{\theta}_\rho := [\rho_o, b]'$ , and from (10) we have

$$\mathbf{J}_\rho = \frac{2\rho_o^2 T}{\sigma_g^2} \begin{bmatrix} \frac{\epsilon_0}{\rho_o} & -\frac{\epsilon_1}{\epsilon_2} \\ -\frac{\epsilon_1}{\rho_o} & \epsilon_2 \end{bmatrix}, \quad (12)$$

$$\epsilon_k := T^{-1} \sum_{t=0}^{T-1} (t/T)^k \exp(-2bt/T), \quad k \geq 0. \quad (13)$$

The diagonal elements of  $\mathbf{J}_\rho^{-1}$  yield the corresponding CRBs,

$$\text{CRB}(\hat{\rho}_o) = \frac{\sigma_g^2}{2T} \frac{\epsilon_2}{\epsilon_0 \epsilon_2 - \epsilon_1^2}, \quad (14)$$

$$\text{CRB}(\hat{b}) = \frac{\sigma_g^2}{2\rho_o^2 T} \frac{\epsilon_0}{\epsilon_0 \epsilon_2 - \epsilon_1^2}. \quad (15)$$

Note that the results of (14) and (15) hold for *any*  $\phi(t)$ , not just polynomials. For the special case of damped harmonics, these results reduce to those in [3]. Note that since each  $\epsilon_k$  is  $O(1)$ , the CRBs in (14) and (15) are both  $O(T^{-1})$ .

Now for the phase parameters, we have

$$J_{\phi, kl} = \frac{2}{\sigma_g^2} \sum_{t=0}^{T-1} \rho^2(t/T) \frac{\partial \phi(t)}{\partial \theta_{\phi_k}} \frac{\partial \phi(t)}{\partial \theta_{\phi_l}}. \quad (16)$$

Unlike  $J_{\rho, kl}$ ,  $J_{\phi, kl}$  in (16) can be  $O(T^m)$  for different  $m$ 's depending on the specific choice of  $\phi(t)$ . For the polynomial phase function  $\phi(t) = \sum_{m=0}^M a_m t^m$ , which is of interest in this paper,  $\theta_{\phi_k} := a_k$ , and  $\partial \phi(t)/\partial a_k = t^k$ . From (16), we conclude that for  $k, l = 0, 1, \dots, M$ ,

$$J_{\phi, kl} = \frac{2T^{k+l+1}}{\sigma_g^2} \frac{1}{T} \sum_{t=0}^{T-1} (t/T)^{k+l} \rho^2(t/T) \quad (17)$$

$$\rightarrow \frac{2T^{k+l+1}}{\sigma_g^2} \int_0^1 u^{k+l} \rho^2(u; \underline{\theta}_\rho) du; \quad (18)$$

hence,  $J_{\phi, kl} = O(T^{k+l+1})$ . The inverse of the  $(M+1) \times (M+1)$  FIM  $\mathbf{J}_\phi$ , whose  $(k, l)$  entry is given by (17), therefore yields  $\text{CRB}(\hat{a}_m) = O(T^{-2m-1})$  as diagonal elements.

Exponentially damped chirp ( $M = 2$ ) processes are of particular interest in applications such as Vibroseis. For such a process, eq. (17) yields for  $k, l = 0, 1, 2$ ,

$$\mathbf{J}_\phi = \frac{2\rho_o^2 T}{\sigma_g^2} \begin{bmatrix} \epsilon_0 & T \epsilon_1 & T^2 \epsilon_2 \\ T \epsilon_1 & T^2 \epsilon_2 & T^3 \epsilon_3 \\ T^2 \epsilon_2 & T^3 \epsilon_3 & T^4 \epsilon_4 \end{bmatrix}, \quad (19)$$

where  $\epsilon_k$  is given by (13). The diagonal elements of  $\mathbf{J}_\phi^{-1}$  are

$$\text{CRB}(\hat{a}_0) = \frac{\sigma_g^2}{2\rho_o^2} \frac{\epsilon_2 \epsilon_4 - \epsilon_3^2}{TD}, \quad (20)$$

$$\text{CRB}(\hat{a}_1) = \frac{\sigma_g^2}{2\rho_o^2} \frac{\epsilon_0 \epsilon_4 - \epsilon_2^2}{T^3 D}, \quad (21)$$

$$\text{CRB}(\hat{a}_2) = \frac{\sigma_g^2}{2\rho_o^2} \frac{\epsilon_0 \epsilon_2 - \epsilon_1^2}{T^5 D}, \quad (22)$$

where  $D := \epsilon_0 \epsilon_2 \epsilon_4 - \epsilon_1^2 \epsilon_4 - \epsilon_0 \epsilon_3^2 + 2\epsilon_1 \epsilon_2 \epsilon_3 - \epsilon_2^3$ . It follows that the CRBs in (20), (21), and (22) are  $O(T^{-1})$ ,  $O(T^{-3})$ , and  $O(T^{-5})$ . Moreover, the CRBs for the constant amplitude chirp model ( $b = 0$ ) can be obtained from (20)-(22) with  $\epsilon_k \approx T/(k+1)$ , and are given by  $\text{CRB}(\hat{a}_0) \approx 4.5\sigma_g^2/(T\rho_o^2)$ ,  $\text{CRB}(\hat{a}_1) \approx 96\sigma_g^2/(T^3\rho_o^2)$ ,  $\text{CRB}(\hat{a}_2) \approx 90\sigma_g^2/(T^5\rho_o^2)$ . These results agree with those in [1].

### 4. MULTI-COMPONENT PPS AND HAF

The HIM is a nonlinear operator, hence it is expected that cross terms appear when one computes the HIM of a multi-component process. In general,  $\mathcal{P}_M$  of an  $L$ -component signal introduces as many as  $L^2 M^{-1} - L$  cross terms, which is 2 for  $L = M = 2$ , and is 14 for  $L = 2, M = 3$ . The objective of this section is to argue that the cross terms almost always disappear in the HAF domain; i.e., after the limiting FS operation. This implies that the HAF of a multi-component PPS can almost always be approximated by the sum of HAFs of individual PPS components.

For simplicity, we discuss here the two component ( $L = 2$ ) case and constant amplitude PPS. Results for general multi-component and/or TV amplitude PPS follow similarly. We start with chirp signals ( $M = 2$ ), which are modeled in discrete-time as,

$$s(t) = \rho_1 e^{j(a_{12}t^2 + a_{11}t + a_{10})} + \rho_2 e^{j(a_{22}t^2 + a_{21}t + a_{20})}. \quad (23)$$

We assume w.l.o.g. that  $\rho_1, \rho_2$  are real, and  $\rho_1 > \rho_2 > 0$ . The instantaneous 2nd-order moment of (23) is given by:

$$\mathcal{P}_2[s(t); 1] = \rho_1^2 e^{2ja_{12}t} e^{j(a_{11}-a_{12})} + \rho_2^2 e^{2ja_{22}t} e^{j(a_{21}-a_{22})} \quad (24)$$

$$+ 2\rho_1 \rho_2 e^{j(a_{12}-a_{22})t^2 + j(a_{11}-a_{21}+2a_{22})t + j(a_{21}-a_{22}+a_{10}-a_{20})} \quad (25)$$

$$+ 2\rho_1 \rho_2 e^{j(a_{22}-a_{12})t^2 + j(a_{21}-a_{11}+2a_{12})t + j(a_{11}-a_{12}+a_{20}-a_{10})}. \quad (26)$$

The "auto" terms in (24) are the 2nd-order HIM of the individual components and produce spectral lines at  $\alpha = 2a_{12}$  and  $2a_{22}$  with magnitudes  $\rho_1^2$  and  $\rho_2^2$  respectively. We are interested in evaluating the contributions of the cross terms (25) and (26) to the HAF,  $\mathcal{P}_2[s; \alpha, 1]$ . Such contributions have been characterized as non-random noise.

Since a factor  $\exp(j\omega_0 t)$  only shifts spectral lines in the FS domain, and  $\exp(j\phi_0)$  has no effect on the magnitude, we shall focus on the behavior of  $\text{FS}[\exp(j\nu_2 t^2)]$  only, where  $\nu_2 := a_{12} - a_{22}$ .

Surprisingly, although  $\exp(j\nu_2 t^2)$  is aperiodic in continuous time  $\forall \nu_2$ , it is periodic in discrete-time for  $\nu_2 = 2\pi N/D$ , where  $N, D$  are co-prime integers. To see this, recall that any integer  $t$  can be written as  $t = iD + k$ , where  $i = [t/D]$ , and  $k \in [0, D - 1]$ . It follows easily that

$$e^{j\nu_2 t^2} = e^{j2\pi(k^2 + 2iDk + i^2 D^2)N/D} = e^{j2\pi k^2 N/D}, \quad (27)$$

which is periodic. It turns out [12] that when  $D$  is a multiple of 4, then  $D/2$  is the period, otherwise  $D$  is the period. Since  $\exp(j2\pi t^2 N/D)$  is periodic, its FS coefficient, denoted as  $h(\alpha)$ , contains spectral lines. We can show that when  $D$  is even,  $h(\alpha)$  consists of  $D/2$  lines, and  $\max_\alpha |h(\alpha)| = \sqrt{2/D}$ ; whereas when  $D$  is odd,  $h(\alpha)$  consists of  $D$  lines, and  $\max_\alpha |h(\alpha)| = \sqrt{1/D}$ .

Because line spectra are produced only when  $\nu_2$  is of the form  $2\pi$  times a rational, and rational numbers have measure zero, we conclude that lines almost never occur in  $h(\alpha)$ . One may argue that since any real number can be approximated arbitrarily closely by a rational number, line spectra should be seen frequently. Our answer is that  $D$  has to be sufficiently large to obtain a good approximation, and as  $D \rightarrow \infty$ , the peak strength  $\sqrt{2/D}$  or  $\sqrt{1/D}$  goes to zero, and hence there will be no lines. If significant lines do show up,  $\nu_2$  must be of the form  $2\pi N/D$  with  $D$  small. Therefore we assert that in general cross terms do not confuse the spectral lines which are due to individual PPS components, and the HAF is essentially additive.

From (24)-(26), if  $\rho_1^2$  is always larger than  $2\rho_1\rho_2$  times the maximum of  $|h(\alpha)|$ , due to the cross terms, then one can always correctly identify the largest signal component, estimate its parameters, remove this component, and reduce the number of components by one [5]. The condition stated in [5] for this to be feasible is  $\rho_1/\rho_2 > 2$ . We show next that one can significantly weaken this constraint.

First, with  $\tau = 1$ , the leading chirp coefficients must satisfy  $|a_{12}| < \pi/2$  and  $|a_{22}| < \pi/2$  in order to satisfy the HAF-based identifiability conditions. This implies that  $|\nu_2| = |a_{12} - a_{22}| < \pi$ , and hence  $N/D < 1/2$ . Assume  $\rho_1/\rho_2 > 1$ ; next, we identify the worst case scenarios which put additional constraints on  $\rho_1/\rho_2$ : (c1)  $D = 4, N = 1$ ,  $|a_{12} - a_{22}| = \pi/2$ , which requires  $\rho_1/\rho_2 > \sqrt{2}$ , and (c2)  $D = 3, N = 1$ ,  $|a_{12} - a_{22}| = 2\pi/3$ , which requires  $\rho_1/\rho_2 > 2/\sqrt{3}$ . Therefore we conclude that if  $|a_{12} - a_{22}| \neq \pi/2$  or  $2\pi/3$ , then the successive estimation algorithm described in [5] can be implemented, for *any*  $\rho_1/\rho_2 > 1$ . Otherwise, one needs to ensure  $\rho_1/\rho_2 > \sqrt{2}$  or  $2/\sqrt{3}$ . This is a much weaker condition than the one stated in [5].

For a general  $M$ th-order PPS, we prove similarly that  $\exp(j\nu_M t^M)$  is periodic if  $\nu_M = 2\pi N/D$ . For  $M$  prime and  $D$  an integer multiple of  $M^2$ , its period is  $D/M$ ; otherwise, the period is  $D$ . The situation where  $M$  is a composite number will be discussed in [12].

For  $M$ th-order PPS, cross terms in the HIM are of the general form  $\prod_{m=0}^M \exp(j\nu_m t^m)$ , and is periodic only when *every*  $\nu_m$  is of the form  $2\pi N/D$ , which is rather unlikely. Similar arguments can be used to conclude that cross terms do not contribute much to the HAF. Detailed analysis will be provided in [12].

## 5. NON-LINEAR LEAST SQUARES ESTIMATOR

Although the FFT-based HAF method is easy to implement, it is suboptimal; hence, we consider the non-linear least squares estimator (NLLSE), for both the phase and amplitude parameters. The main result is given by Theorem 1, and is a generalization of results by Hasan [3], who considers the pure harmonic, i.e., ( $M = 1$ ) in (7).

Consider the noisy monocomponent model in (7). In addition to (a1) and (a2), conditions (a3) and (a4) below are also assumed to be in force.

(a3). The noise sequence  $g(t)$  is strictly stationary, circularly symmetric (i.e., its real and imaginary parts have the same distribution, and are independent of each other) and purely non-deterministic, with zero mean,  $E|g(t)|^k < \infty$ ,  $k = 0, 1, \dots$ , and satisfies the mixing condition,  $\sum_{\tau} |c_{kg}(\tau)| < \infty$ ,  $k = 2, 3, \dots$ .

(a4). The basic identifiability assumption is:

$$(\theta_\rho = \theta'_\rho) \text{ iff } \int_0^1 |\rho(u; \theta_\rho) - \rho(u; \theta'_\rho)|^2 du = 0 \quad (28)$$

Let  $\underline{\theta}_\phi := [a_0, a_1 T, \dots, a_M T^M]'$ ,  $\underline{\theta} := [\underline{\theta}_\rho, \underline{\theta}_\phi]$ , and let  $\underline{\theta}_o$  denote the true parameters. Note that we have re-defined  $\underline{\theta}_\phi$ . For convenience, we do not explicitly denote the dependence of  $\underline{\theta}_\phi$ ,  $\underline{\theta}$ ,  $\underline{\theta}_o$  and  $s(\cdot)$  upon  $T$ . The NLLSE,  $\hat{\underline{\theta}}$ , minimizes

$$Q_T(\underline{\theta}) := \sum_{t=0}^{T-1} |x(t) - s(t; \underline{\theta})|^2 \quad (29)$$

and can be initialized by estimates obtained from the sub-optimal HAF scheme.

### 5.1. Rate of convergence & Consistency

**Lemma 1** Let  $\hat{\underline{\theta}}$  denote an estimate of  $\underline{\theta}$  based on  $T$  samples. Then,

$$J = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=0}^{T-1} |s(t; \hat{\underline{\theta}}) - s(t; \underline{\theta})|^2 = 0 \quad (30)$$

only if  $\hat{\underline{\theta}}_\rho = \underline{\theta}_\rho + o_p(1)$ , and  $\hat{a}_k = a_k + o_p(T^{-k})$ .  $\square$

**Proof.** Omitted due to lack of space; see [9].

Note that the rate of convergence of the  $k$ -th phase parameter is of order  $1/T^k$ . Consistency of the NLLSE follows directly from Lemma 1 and assumption (a3).

### 5.2. Covariance Expressions

Since the NLLSE is consistent, the Taylor expansion

$$s(t; \hat{\underline{\theta}}) = s(t; \underline{\theta}_o) + (\hat{\underline{\theta}} - \underline{\theta}_o) \nabla_{\underline{\theta}} s(t; \underline{\theta})|_{\underline{\theta}=\underline{\theta}_o} + o_p(1), \quad (31)$$

holds for large  $T$ ; the order  $o_p(1)$  for the remainder term follows from Lemma 1 (recall the rates of convergence, and note the scaling). We substitute (31) and (7) in (29), to obtain a quadratic function in  $\hat{\underline{\theta}} := \hat{\underline{\theta}} - \underline{\theta}_o$ ; the least squares solution is given by the linear system of equations,

$$\tilde{\underline{\theta}} = \mathbf{A}_T^{-1} \mathbf{b}_T \quad (32)$$

where

$$\begin{aligned} A_T(m, n) &:= 2 \operatorname{Real} \sum_{t=0}^{T-1} \frac{\partial s(t; \underline{\theta})}{\partial \theta_m} \frac{\partial s^*(t; \underline{\theta})}{\partial \theta_n} \\ b_T(m) &:= 2 \operatorname{Real} \sum_{t=0}^{T-1} \frac{\partial s(t; \underline{\theta})}{\partial \theta_m} g^*(t) \end{aligned}$$

Vector  $\mathbf{b}_T$  has zero mean; hence  $\tilde{\underline{\theta}}$  has zero mean, and since matrix  $\mathbf{A}_T$  is non-random (and real, symmetric), we have

$$\operatorname{cov}(\tilde{\underline{\theta}}) = E\{\tilde{\underline{\theta}}\tilde{\underline{\theta}}^H\} = \mathbf{A}_T^{-1} \operatorname{cov}(\mathbf{b}_T) \mathbf{A}_T^{-1}. \quad (33)$$

We need to evaluate the asymptotic values of the component terms. We will find it convenient to define the following:

$$\int_0^1 u^{m+n} \rho(u; \underline{\theta}_\rho) \rho(u; \underline{\theta}_\rho) du := \gamma_{m,n}(\underline{\theta}_\rho) \quad (34)$$

$$\int_0^1 \frac{\partial \rho(u; \underline{\theta}_\rho)}{\partial \theta_{\rho,m}} \frac{\partial \rho(u; \underline{\theta}_\rho)}{\partial \theta_{\rho,n}} du := \tilde{\gamma}_{m,n}(\underline{\theta}_\rho) \quad (35)$$

$$\int_0^1 \left| \frac{\partial \rho(u; \underline{\theta}_\rho)}{\partial \theta_{\rho,m}} \frac{\partial \rho(u; \underline{\theta}_\rho)}{\partial \theta_{\rho,n}} \right| du := \vartheta_{m,n}(\underline{\theta}_\rho) \quad (36)$$

$$\int_0^1 \left| \frac{\partial \rho(u; \underline{\theta}_\rho)}{\partial \theta_{\rho,m}} \right| \rho(u; \underline{\theta}_\rho) u^n du := \tilde{\vartheta}_{m,n}(\underline{\theta}_\rho) \quad (37)$$

By assumptions (a1)-(a2), the elements of the matrix  $T^{-1} \mathbf{A}_T$  are given asymptotically by,

$$\mathbf{H} := \lim_{T \rightarrow \infty} \frac{1}{T} \mathbf{A}_T = 2 \begin{bmatrix} \{\tilde{\gamma}_{k,\ell}(\underline{\theta}_\rho)\} & \mathbf{0} \\ \mathbf{0} & \{\gamma_{m,n}(\underline{\theta}_\rho)\} \end{bmatrix} \quad (38)$$

where  $\tilde{\gamma}_{k,\ell}$  and  $\gamma_{m,n}$  are defined in (34) and (35);  $k, \ell$  range from 1 to  $N_\rho$ , the number of amplitude-related parameters, and  $m, n$  range from 0 to  $M$ . Notice that matrix  $\mathbf{H}$  is block-diagonal: the amplitude and phase parameters are uncoupled.

The  $(m, n)$  element of the covariance matrix,  $\mathbf{C}_{b,T}$ , of the zero-mean  $\mathbf{b}_T$  is given by

$$\mathbf{C}_{b,T}(m, n) = 2 \operatorname{Re} \sum_{t=0}^{T-1} \sum_{u=0}^{T-1} R_g(t-u) \frac{\partial s^*(t; \underline{\theta})}{\partial \theta_m} \frac{\partial s(u; \underline{\theta})}{\partial \theta_n} \quad (39)$$

where  $R_g(\tau) = E\{g^*(t)g(t+\tau)\}$ ; two terms have dropped out since circular symmetry implies  $E\{g(t)g(t+\tau)\} = 0$ .

For the amplitude parameters, we have to evaluate

$$\beta_T := \sum_{t=-T+1}^{T-1} \sum_{u=0}^{T-1} R_g(t) \frac{\partial \rho(\frac{t+u}{T}; \underline{\theta}_\rho)}{\partial \theta_{\rho,m}} \frac{\partial \rho(\frac{u}{T}; \underline{\theta}_\rho)}{\partial \theta_{\rho,n}} \times e^{j\phi(u; \underline{\theta}_\phi) - j\phi(t+u; \underline{\theta}_\phi)}.$$

For  $M > 2$ , it is generally hard to evaluate  $\beta_T$ , since  $\exp(j\phi(t))$  is not of bounded variations. Let

$$\bar{\sigma}_g^2 := \sum_{\tau=-\infty}^{\infty} |R_g(\tau)| < \infty, \quad (40)$$

where the inequality follows by Assumption (a3). Now,

$$|\beta_T| \leq \sum_{t=0}^{T-1} \sum_{u=0}^{T-1} |R_g(t)| \left| \frac{\partial \rho(\frac{t+u}{T}; \underline{\theta}_\rho)}{\partial \theta_{\rho,m}} \frac{\partial \rho(\frac{u}{T}; \underline{\theta}_\rho)}{\partial \theta_{\rho,n}} \right| \approx T \bar{\sigma}_g^2 \vartheta_{m,n}(\underline{\theta}_\rho).$$

Similarly, for the phase parameters, we obtain the upper bound  $T \bar{\sigma}_g^2 \gamma_{m,n}(\underline{\theta}_\rho)$ . For the cross-parameters,  $\theta_{\rho_k}$  and  $\theta_{\phi_l}$ , we obtain the bound  $T \bar{\sigma}_g^2 \tilde{\vartheta}_{k,\ell}(\underline{\theta}_\rho)$ .

If  $g(t)$  is white,  $R_g(t-u) = \sigma_g^2 \delta(t-u)$ ; the double summation in (39) collapses to a single summation over  $t = u$ , and it is easy to show that the amplitude and phase parameters are decoupled. Using (34) and (35), we obtain  $\mathbf{C}_{b,T} = T \sigma_g^2 \mathbf{H}$ , and

$$\operatorname{cov}(\hat{\underline{\theta}}) \approx \frac{\sigma_g^2}{T} \mathbf{H}^{-1}. \quad (41)$$

These results reduce to those of Peleg-Porat who consider the special case of a Gaussian  $g(t)$ , and  $\rho(u; \underline{\theta}_\rho) \equiv \rho_0$ . Note that the matrix  $\mathbf{H}$  is a Hilbert matrix in the constant amplitude case; we can obtain approximations for moderate sample sizes by retaining terms of order  $O(1)$  in  $\mathbf{H}$ . Our results are summarized in Theorem 1.

**Theorem 1** Under assumptions (a1)-(a4), the NLLSE is asymptotically normal and unbiased. If  $g(t)$  is white, the covariance matrix is given by

$$\operatorname{cov}(\hat{\underline{\theta}}) \approx \frac{\sigma_g^2}{T} \mathbf{H}^{-1} \quad (42)$$

where matrix  $\mathbf{H}$  is defined in (38). In the case of colored noise, we obtain an element-wise upper bound

$$\operatorname{cov}(\hat{\underline{\theta}}) \leq \frac{\sigma_g^2}{T} |\mathbf{H}^{-1}| \mathbf{H}_c |\mathbf{H}^{-1}| \quad (43)$$

where  $|A|$  denotes the absolute value and  $0 \leq$  denotes element-wise inequality, and

$$\mathbf{H}_c := 2 \begin{bmatrix} \{\vartheta_{k,\ell}(\underline{\theta}_\rho)\} & \{\tilde{\vartheta}_{k,n}(\underline{\theta}_\rho)\} \\ \{\tilde{\vartheta}_{\ell,m}(\underline{\theta}_\rho)\} & \{\gamma_{m,n}(\underline{\theta}_\rho)\} \end{bmatrix}; \quad (44)$$

where  $\gamma$ ,  $\tilde{\gamma}$ ,  $\vartheta$  and  $\tilde{\vartheta}$  are defined in (34)-(37), and  $\bar{\sigma}_g^2$  in (40). The elements of matrices  $\mathbf{H}$  and  $\mathbf{H}_c$  are evaluated at the true parameter vector  $\underline{\theta}_0$ .  $\square$

Based on Theorem 1, we assert that each parameter in  $\underline{\theta}_\rho$  has variance  $O(T^{-1})$ , whereas  $\operatorname{var}(\hat{a}_m) = O(T^{-2m-1})$ . Asymptotic normality follows along the lines of Hasan [3] under assumption (a3). Under the stronger assumption of absolute summability of cumulants of  $g(t)$ , asymptotic normality follows immediately from the ergodicity results of Dandawate-Giannakis (by assumptions (a1)-(a2), the partials of  $s(\cdot)$  are bounded).

The multi-component case is discussed in [9]. It will be seen that the amplitudes and phase parameter estimates are generally not decoupled; and that phase (amplitude) estimates of different components are also not decoupled. Note that even in the case of white noise, the FIM (CRB) is block diagonal only if  $L = 1$  (single component) or  $M = 1$  (pure harmonic). Here the periodicity issues discussed in Section 4. are important.

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