

FAST AND POWER EFFICIENT HARDWARE-ACCELERATED CLOUD-BASED ASR FOR REMOTE DIALOG APPLICATIONS

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ABSTRACT

We demonstrate a GPU-based implementation of an automated speech recognition system that is massively faster, sometimes significantly more accurate and more power-efficient than a modern CPU-based open-source reference. This technology enables speech solution providers to efficiently up-scale their operation to the consumer market. Our GPU-based speech recognition platform supports statistical models, created with publicly available speech toolkits. The platform is cloud-based and capable of supporting online spoken interaction with remote interlocutors as a mass service.

Index Terms— hardware-accelerated speech recognition; dialog interaction with remote interlocutors.

1. INTRODUCTION

Apart from the accuracy, a successful mass automated speech recognition (ASR) service requires excellent processing speed and energy efficiency. For such use cases as serving a spoken dialog system (SDS) and mining user’s audio data for specific keywords, the processing speed is even more important [1].

Processing speedup is achievable via committing larger areas of the die for solving a single task. In the multi-core CPU programming model that is accomplished by construction of multi-threaded programs that are sharing common data. Graphical processing units (GPUs) allow for an easier processing resource management. The GPU chip lacks extensive control logic making it potentially more efficient. The downside is increase of the programming effort.

Early attempts at parallelization of speech recognition with CPUs [2] and GPUs [3, 4] produced encouraging results. There are hybrid realizations involving multi-stage processing via rescore [5]. In contrast our system is a completely GPU-based speech recognizer [6] that is capable of outperforming the CPU implementation even in the full computational occupancy case [7].

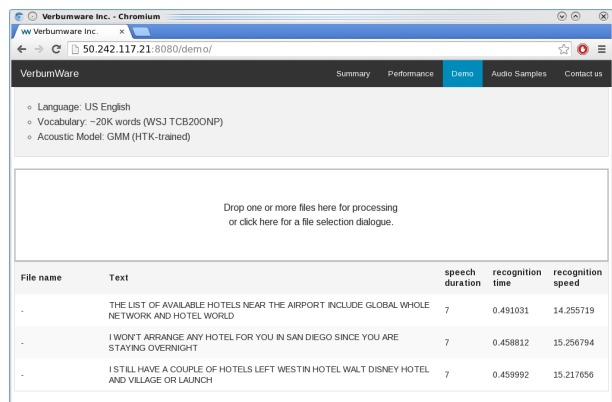
In the following sections we summarize the observed results and outline the system demonstration. The demonstration is performed via accessing the ASR web interface in a general purpose browser (see Fig.1 for a screen shot). Sample audio files are dragged onto the designated area of the

web page for subsequent local playback and recognition by the remote cloud-based ASR server.

2. SYSTEM PERFORMANCE

The “NOV’92” and “NOV’93” evaluation sets of the Wall Street Journal spoken corpus are chosen to illustrate system performance on a range of tasks: 5K word vocabulary of NOV’92 and 20K word vocabulary with a high OOV rate of the DARPA NOV’93 evaluation. We have used the following language models: “bcb05onp” – bi-gram, 5K word “open” vocabulary, “bcb05cnp” – bi-gram, 5K word “closed” vocabulary, “tcb20onp” – tri-gram, 20K word “open” vocabulary.

The measurements are done with the following systems: an Intel Core i7-4930K server system equipped with TITAN X; a mobile system with NVIDIA Tegra K1 processing unit. The TITAN-equipped system is available for public evaluation¹.



File name	Text	speech duration	recognition time	recognition speed
-	THE LIST OF AVAILABLE HOTELS NEAR THE AIRPORT INCLUDE GLOBAL WHOLE NETWORK AND HOTEL WORLD	7	0.491031	14.255719
-	I WON'T ARRANGE ANY HOTEL FOR YOU IN SAN DIEGO SINCE YOU ARE STAYING OVERNIGHT	7	0.458812	15.256704
-	I STILL HAVE A COUPLE OF HOTELS LEFT WESTIN HOTEL WALT DISNEY HOTEL AND VILLAGE OR LAUNCH	7	0.459992	15.217656

Fig. 1. Speech recognition web interface.

Table 1 summarizes recognition results of the deep neural network (DNN) acoustic model trained with the Kaldi toolkit. The GPU-enabled engine accuracy is approximately equal to that of the open-source baseline. There is a small fluctuation of the actual Word Error Rate (WER) due to the arithmetic implementation differences. For a single-channel recognition the TITAN-enabled engine is ≈ 7 times faster than the reference. This is important in tasks like serving ASR to an SDS

¹<http://verbumware.org:8080/demo/>

Task / LM	bc b05onp	bc b05cnp	bc b05onp	bc b05cnp	tc b20onp	bc b05onp	bc b05cnp	tc b20onp
NOV'92 WER	5.66%	2.30%	5.66%	2.30%	1.85%	5.77%	2.19%	1.63%
NOV'92 1/xRT	2.15	2.14	30.58	30.49	27.47	5.08	5.26	4.54
NOV'93 WER	18.22%	19.99%	18.22%	19.99%	7.77%	18.13%	20.19%	7.63%
NOV'93 1/xRT	2.15	2.15	30.12	30.21	26.67	4.33	4.20	3.90
Power, W/RTchan.	3.6		9			15		
Hardware	Tegra K1 (32 bit)		GeForce GTX TITAN BLACK			i7-4930K @3.4GHz		
	Hardware-accelerated					nnet-latgen-faster		

Table 1. Performance of the hardware accelerated version of the DNN-HMM system vs Nnet-latgen-faster decoder baseline.

Task / LM	bc05onp	bc05cnp	tc20onp	bc05onp	bc05cnp	tc20onp
NOV'92 WER	9.27%	5.47%	4.50%	9.30%	5.59%	5.64%
NOV'92 1/xRT	16.67	16.76	15.25	0.30	0.30	0.25
NOV'93 WER	28.05%	26.72%	11.66%	27.88%	26.46%	13.37%
NOV'93 1/xRT	16.49	16.58	15.04	0.25	0.25	0.19
Power, W/RTchan.	20			260		
Hardware	GeForce GTX TITAN X			i7-4930K @3.4GHz		
	Hardware-accelerated			HTK HDecode		

Table 2. Performance of the hardware accelerated version of the GMM-HMM system vs HTK HDecode.

or media-mining for specific spoken events. The implementation in the mobile device (NVIDIA Tegra K1) enables twice faster than real-time (RT) processing without any degradation in accuracy. The GPU-enabled engine allows unprecedented energy efficiency. The value of 15W per one RT channel was estimated while the CPU was fully loaded with 12 concurrent recognition jobs. That is the most power efficient manner of CPU utilization [7]. The TITAN-enabled server does better (9 W per one RT channel) while maintaining its processing speed. The Tegra-based solution is several times more efficient (3.6 W per one RT channel). The power per one RT channel was estimated as system's average cumulative consumption adjusted by the processing realtime factor and the number of concurrent processes. Power consumption and recognition speed of the GPU-based solution are linearly proportional to the system's load. On the contrary, the CPU consumes much more energy (per channel) when operating at the maximum pace, i.e. working on a single channel.

A Gaussian Mixture Model-Hidden Markov Model (GMM-HMM) system behaves similarly. Comparison of the GPU implementation to the HTK toolkit reference is given in Table 2. The bi-gram LM accuracy is roughly the same. With the tri-gram LM (tc20onp) accuracy is significantly better. The hardware-accelerated speech recognition system is massively faster (from 55 to 80 times). The hardware-accelerated recognition speed with the optimal parameter set does not depend much on the total search network size, which suggests efficiency of the search implementation.

3. CONCLUSIONS

The experiment presented in this paper has proven our conjecture about the possibility to build a faster ASR via committing larger areas of the die for solving a single speech recognition task. The GPU utilization (according to the nvidia-smi utility) is about 85 %.

The resulting system is suitable for faster than RT serving

remote SDS applications from the cloud. Alternatively, the same system can be used for achieving RT processing speed with more complex statistical models.

4. ACKNOWLEDGMENTS

We would like to express our gratitude to NVIDIA that supported this work with advice and supplied us with various types of the latest computing hardware.

This work would not have been possible without contributions of Fabio Brugnara of Fondazione Bruno Kessler, Trento, Italy who provided insights, expertise and experience that greatly facilitated creation of the demonstrated system.

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